L Number	Hits	Search Text	DB	Time stamp
-	194	(382/152).CCLS.	USPAT; US-PGPUB	2004/03/15 15:34
_	2	WO-9942257-\$.did.	USPAT;	2004/03/15
			US-PGPUB; EPO; JPO;	15:57
			DERWENT	
-	2	WO-9201539-\$.did.	USPAT;	2004/03/15
			US-PGPUB; EPO; JPO;	15:57
	:		DERWENT	
-	6		USPAT;	2004/03/15 16:09
_	33	4725965.pn. 4985846.pn. 5297238.pn. ((382/152).CCLS.) and robot	US-PGPUB USPAT;	2004/03/15
			US-PGPUB	16:54
-	51	((382/151).CCLS.) and robot	USPAT; US-PGPUB	2004/03/15 16:55
-	7	arimatsu-taro.in.	USPAT;	2004/03/15
	144	watanabe-atsushi.in.	US-PGPUB USPAT;	16:57 2004/03/15
-	144	watanabe-atsusni.in.	US-PGPUB	16:57
-	7	382/141-154;901/47.ccls. and	USPAT; US-PGPUB	2004/03/15 16:58
_	61	watanabe-atsushi.in. (robot) same (plural\$3 or multiple or	USPAT;	2004/03/15
	0.2	dual or two or several or many) adj	US-PGPUB	16:58
		(video or camera or CCD or image or visual) same (workpiece or work-piece or		
		work adj piece or part or model)		
-	10	((382/154).CCLS.) and (reference or register\$3 or registration or teach\$3 or	USPAT; US-PGPUB	2004/03/15 16:59
		train\$3 or learn\$3) with (object or model	05 10105	10.03
		or part or workpiece or work-piece or work adj piece) same robot		
_	64	(robot) same (video or camera or CCD or	USPAT;	2004/03/15
		image or visual) same (predetermined or	US-PGPUB	16:59
		known or specifi\$2 or determined) near distance		
-	28	robot same (2-D or two-D or	USPAT;	2004/03/17
		two-dimension\$2 or "2"-dimension\$2 or bi-dimensional or (two or "2") adj	US-PGPUB	09:31
		dimension\$2) with distance		0004/00/15
-	16	robot same (reference or register\$3 or registration or teach\$3 or train\$3 or	USPAT; US-PGPUB	2004/03/15 16:59
		learn\$3) same (video or camera or CCD or		
		image or visual) same (predetermined or known or specifi\$2 or determined) near		
		distance		
-	62	((901/47).CCLS.) and (registration or teach\$3 or train\$3 or learn\$3) with	USPAT; US-PGPUB	2004/03/15 16:59
		(model or part or workpiece or work adj	05 16100	10.05
	100	piece)	USPAT;	2004/03/16
-	109	(382/153).CCLS.	US-PGPUB	14:00
-	169	(382/\$.ccls. 348/\$.ccls. 356/\$.ccls.	USPAT;	2004/03/17
		700/\$.ccls. 901/\$.ccls.) and robot\$3 same (camera or CCD or imag\$3 or video) same	US-PGPUB	09.32
		(position\$3 or locat\$4 or (three or "3")		
		adj dimension\$2 or 3D or coordinate) with (orientation or posture or attitude or		
		pose) with (object or workpiece or work		
		adj piece or part or bin or pile\$1 or article or body)		
-	1		USPAT;	2004/03/17
	1	("A 727 A71") DN	US-PGPUB USPAT;	09:52
-	1	("4,727,471").PN.	US-PGPUB	13:55

-	27	robot\$3 same (camera or CCD or imag\$3 or	USPAT;	2004/03/17
		video) same (orientation or posture or	US-PGPUB	13:25
		attitude or pose) with (object or		
İ		workpiece or work adj piece or part or		
i .		bin or pile\$1 or article or body) same		
1		(reference or model or register\$3 or		
1		registration or template or stored) with]
		(compar\$5 or match\$3 or correlat\$3 or		
		correspond\$3)		1
l -	l 5	JP-05127722-\$.did. JP-07270137-\$.did.	USPAT;	2004/03/18
		JP-07319525-\$.did.	US-PGPUB;	15:21
			EPO; JPO;	
			DERWENT;	
			IBM TDB	